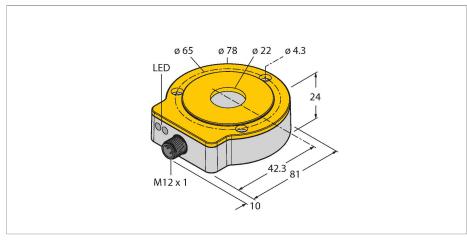


RI360P0-QR24M0-ELIU5X2-H1151 Contactless Encoder – Analog Premium Line



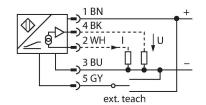
Technical data

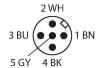
Туре	RI360P0-QR24M0-ELIU5X2-H1151
ID	1590908
Measuring principle	Inductive
General data	
Max. Rotational Speed	12000 rpm
	Determined with standardized construction, with a steel shaft \emptyset 20 mm, L = 50 mm and reducer \emptyset 20 mm
Starting torque shaft load (radial / axial)	not applicable, because of contactless measuring principle
Resolution	16 bit
Measuring range	0360 °
Nominal distance	1.5 mm
Repeat accuracy	≤ 0.01 % of full scale
Linearity deviation	≤ 0.05 % f.s.
Temperature drift	≤ ± 0.004 % / K
Output type	Absolute singleturn
Resolution singleturn	16 Bit
Electrical data	
Operating voltage	1530 VDC
Residual ripple	≤ 10 % U _{ss}
Isolation test voltage	≤ 0.5 kV
Short-circuit protection	yes
Wire breakage/Reverse polarity protection	yes / yes (voltage supply)
Output function	5-pin, Analog output
Voltage output	010 V

Features

- Compact, rugged housing
- Many mounting possibilities
- Status displayed via LED
- Measuring range indicated via LED
- ■Immune to electromagnetic interference
- Measuring range programmable via Easy Teach
- Output signal programmable via Easy Teach
- Resolution, 16-bit
- ■15...30 VDC
- ■0...10 V and 4...20 mA
- Male M12 x 1, 5-pin

Wiring diagram





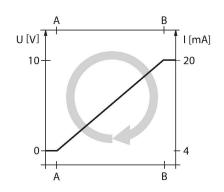
Functional principle

The measuring principle of inductive angle sensors is based on oscillation circuit coupling between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. The rugged sensors are wear and maintenance-free, thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures a high immunity to electromagnetic DC and AC fields.



Technical data

Current output	420 mA	
Diagnostic	Positioning element not within detection range: Output signal 24 mA or 11 V	
Load resistance voltage output	≥ 4.7 kΩ	
Load resistance current output	≤ 0.4 kΩ	
Sample rate	5000 Hz	
Current consumption	< 50 mA	
Mechanical data		
Design	QR24	
Dimensions	81 x 78 x 24 mm	
Flange type	Flange without mounting element	
Shaft Type	Hollow shaft	
Shaft diameter D [mm]	6 6.35 9.525 10 12 12.7 14 15.875 19.05	
Housing material	Metal/plastic, ZnAlCu1/PBT-GF30-V0	
Electrical connection	Connector, M12 × 1	
Environmental conditions		
Ambient temperature	-25+85 °C	
	Acc. to UL approval to +70 °C	
Vibration resistance	55 Hz (1 mm)	
Vibration resistance (EN 60068-2-6)	20 g; 103000 Hz; 50 cycles; 3 axes	
Shock resistance (EN 60068-2-27)	100 g; 11 ms ½ sine; 3 × each; 3 axes	
Continuous shock resistance (EN 60068-2-29)	40 g; 6 ms ½ sine; 4000 × each; 3 axes	
Protection class	IP68 IP69K	
MTTF	138 years acc. to SN 29500 (Ed. 99) 40 °C	
Power-on indication	LED, Green	
Measuring range display	LED, yellow, yellow flashing	
Included in delivery	MT-QR24 mounting aid	

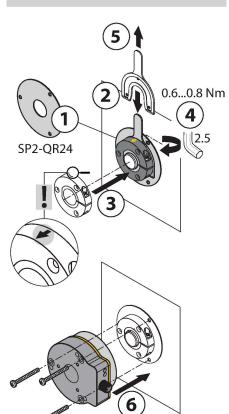




Mounting instructions

Mounting instructions/Description

A

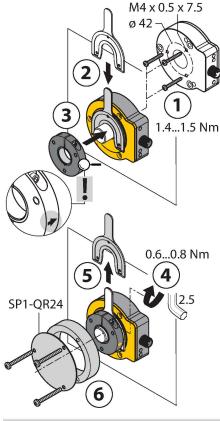


0.6...0.8 Nm

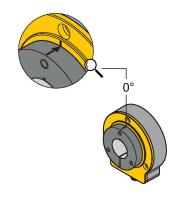
SP3-QR24

0.6...0.8 Nm

В



Default: 0°



Extensive range of mounting accessories for easy adaptation to many different shaft diameters. Based on the functional principle of RLC coupling, the sensor operates absolutely wear-free and is immune to magnetized metal splinters and other interference fields. Wrong installation is hardly possible.

The adjacent figure shows the two separate units, sensor and positioning element.

Mounting option A:

First, interconnect positioning element and rotatable shaft. Then place the encoder above the rotating part in such a way that you get a tight and protected unit.

Mounting option B:

Push the encoder on the back site of the shaft and fasten it to the machine. Then clamp the positioning element to the shaft with the bracket.

Mounting option C:

If the positioning element is to be screwed on a rotating machine part, use the RA0-QR24 plug which is included in the delivery. Then tie up the bracket. Screw on the encoder via the three bores.

The separately arranged sensor and positioning element inhibit that compensating currents or damaging mechanical loads are transmitted via the shaft to the sensor. In addition, the encoder remains tight and highly protected during its entire lifespan.

The accessories enclosed in the delivery help to mount encoder and positioning element at an optimal distance from each other. LEDs indicate the switching status.

Status display via LED green steady: Optimal sensor supply

yellow steady:

Positioning element has reached the end of the measuring range. This is indicated by a lower signal quality.

yellow flashing:

Positioning element is outside the measuring range.

off:

Positioning element is in the measuring range.

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Individual Parameterization	(Teaching	with	Positioning	Flamont)
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marriada i arameterization (readining marri editorining zionient)					
Bridge between teach	Gnd Pin 3 (BU)	Ub Pin1 (BN)	LED		
input Pin 5 (GY)					
2 s	Start value	End value	Status LED flashes then		
			turns steady after 2 s		
10 s	CCW rotation, then	CW rotation, then return to	After 10 s status LED		
	return to last preset	last preset value	flashes fast for 2 s		
	value				
15 s	-	Factory setting (360°, CW)	after 15 s power and		
			status LED alternate		

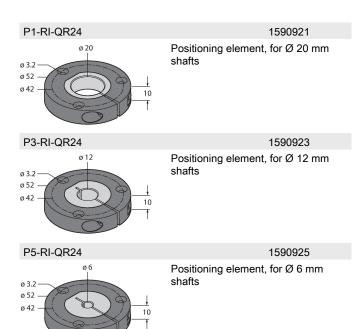
To avoid unintended teaching, keep pin 5 potential-free.

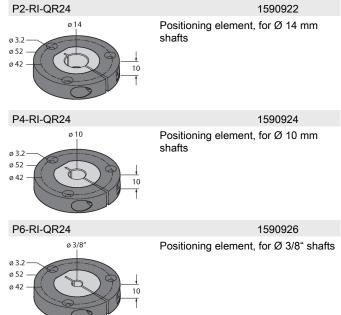
Preset Parameterization (Teaching without Positioning Element)

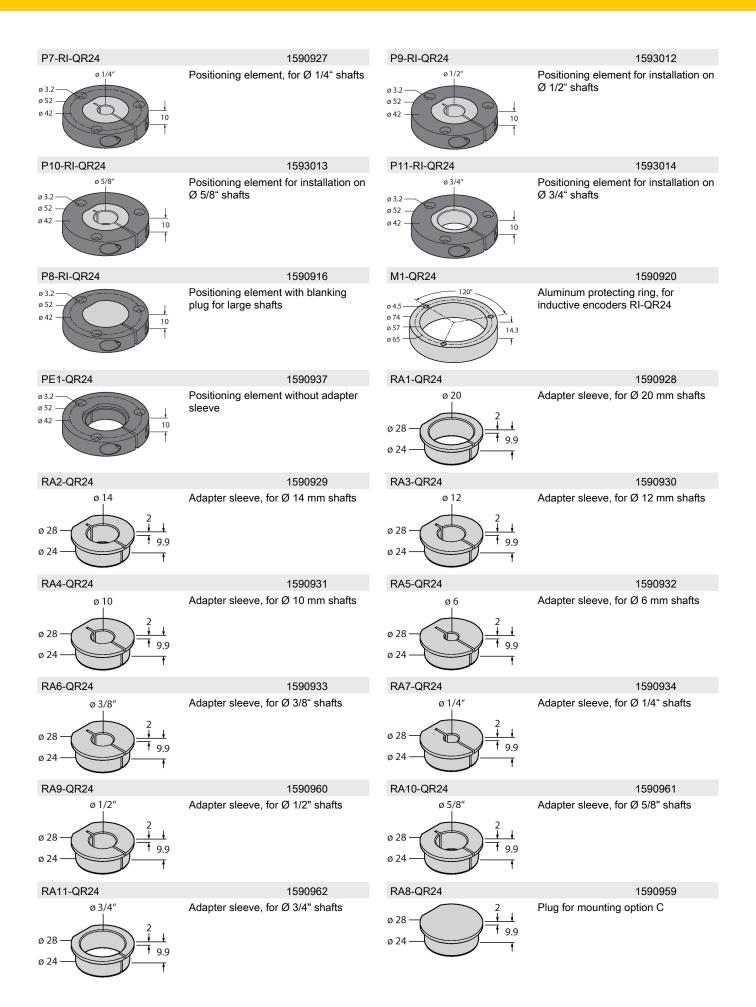
	eaching without Positioning E	, , ,	
Bridge pin between	Gnd Pin 3 (BU)	Ub Pin 1 (BN)	LED
teach input Pin 5 (GY)			
2 s	Activate selection	Activate preset mode (for	Status LED steady,
	mode for output signal	10 s)	flashes after 2 s
	(for 10 s)		
10 s	CCW rotation direction	CW rotation direction	After 10 s status LED
			flashes fast for 2 s
15 s		Factory setting (360°, CW)	After 15 s power and
			status LED flash equally
			fast
Output configuration	Gnd Pin 3 (BU)		Status LED
I out: 420 mA	Press once		1 x flashing
I out: 020 mA	Press twice		2 x flashing
Uout: 010 V	Press three times		3 x flashing
Uout: 05 V	Press four times		4 x flashing
Uout: 0.5 V / 4.5 V	Press five times		5 x flashing
Preset mode / Angular		Ub Pin 1 (BN)	Status LED
range			
45°		Press once	1 x flashing
60°		Press twice	2 x flashing
90°		Press three times	3 x flashing
4000		Droop four times	4 v flashing
180° 270°		Press four times	4 x flashing

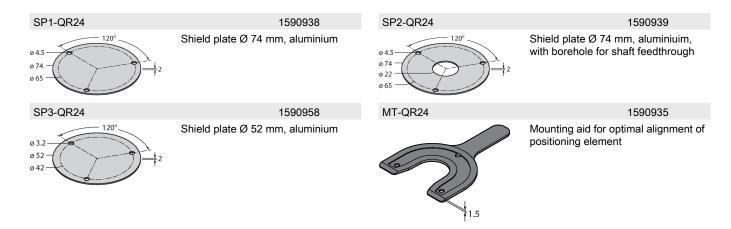
To avoid unintended teaching, keep pin 5 potential-free.

Accessories









Accessories

